

Conditional GANs and their generalizability in physics-based inverse problems

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- ▶ Challenges with Bayesian inference
- ▶ Conditional generative adversarial networks (cGANs)
- ▶ Deep posteriors with cGANs
- ▶ Generalizability
- ▶ Conclusion

Consider a forward problem

$$\mathcal{F} : \mathbf{x} \in \Omega_x \mapsto \mathbf{y} \in \Omega_y, \quad \Omega_x \in \mathbb{R}^{N_x}, \quad \Omega_y \in \mathbb{R}^{N_y}$$

For example the **heat conduction** PDE:

$$\frac{\partial u(\mathbf{s}, t)}{\partial t} - \kappa \Delta u(\mathbf{s}, t) = 0$$

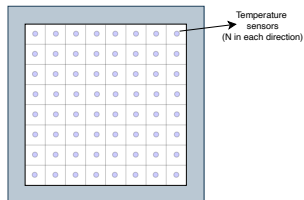
where

$$u(\mathbf{s}, 0) = u_0(\mathbf{s})$$

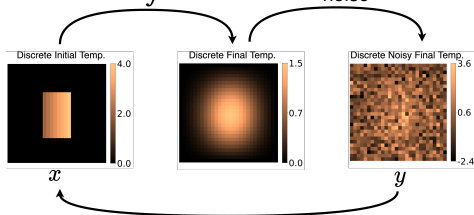
$u(\mathbf{s}, t)$ → temperature at location \mathbf{s} at time t

$u_0(\mathbf{s})$ → initial temperature at location \mathbf{s}

κ → thermal conductivity of material



Inverse problem \mathcal{F}^{-1} : Given **noisy** $u(\mathbf{s}, T)$ infer $u_0(\mathbf{s})$



Challenges with inverse problems:

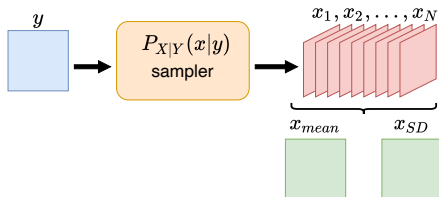
- ▶ Inverse map is **not well posed**.
- ▶ **Noisy measurements**.
- ▶ Need to encode **prior knowledge** about x .

Bayesian framework: x and y modelled by random variables X and Y .

AIM: Given a measurement $Y = y$ approximate the conditional (posterior) distribution

$$P_{X|Y}(x|y)$$

and sample from it.



- ▶ Posterior sampling techniques, such as Markov Chain Monte Carlo, are prohibitively expensive when **dimension of X is large**.
- ▶ Characterization of **priors for complex data**

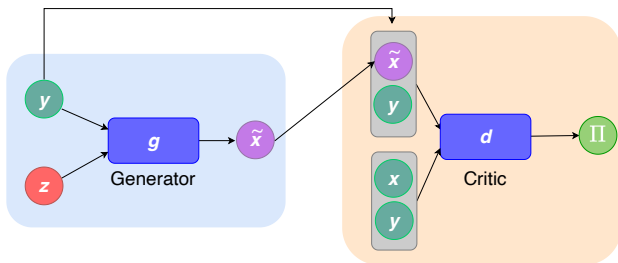
For example, x data might look like:



Representing this data using simple distributions is **hard!**

Resolve both issues using deep learning

- ▶ Learning distributions conditioned on another field.
- ▶ Comprises two neural networks, g and d .



Generator network:

- ▶ $g : \Omega_z \times \Omega_y \rightarrow \Omega_x$.
- ▶ Latent variable $\mathbf{Z} \sim P_Z$, e.g. $N(0, \mathbf{I})$. Also $N_z \ll N_x$.
- ▶ (\mathbf{x}, \mathbf{y}) sampled from true P_{XY}

Critic network:

- ▶ $d : \Omega_x \times \Omega_y \rightarrow \mathbb{R}$.
- ▶ d tries to detect fake samples.
- ▶ $d(\mathbf{x}, \mathbf{y})$ large for real \mathbf{x} , small otherwise.

- ▶ Given $Y = y$ and $Z \sim P_Z$ we get a random variable

$$X^g = g(Z, y), \quad X^g \sim P_{X|Y}^g.$$

- ▶ Objective function

$$\Pi(g, d) = \mathbb{E}_{\substack{(X, Y) \sim P_{XY} \\ Z \sim P_Z}} [d(X, Y) - d(g(Z, Y), Y)]$$

- ▶ g and d determined (with constraint $\|d\|_{\text{Lip}} \leq 1$) through

$$(g^*, d^*) = \arg \min_g \arg \max_d \Pi(g, d)$$

- ▶ Adler et al. (2018) proved that the minmax problem is equivalent to

$$g^* = \arg \min_g \mathbb{E}_{Y \sim P_Y} [W_1(P_{X|Y}, P_{X|Y}^g)]$$

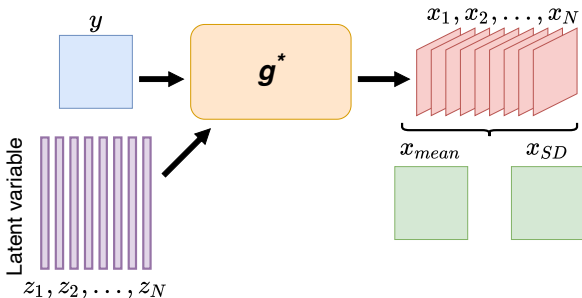
where W_1 is the Wasserstein-1 distance.

Steps:

- ▶ Acquire samples $\mathcal{S}_x = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$, where $\mathbf{x}_i \sim P_X^{\text{prior}}$.
- ▶ Use forward map \mathcal{F} to generate paired dataset

$$\mathcal{S} = \{(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_N, \mathbf{y}_N)\} \quad \text{where} \quad \mathbf{y}_n = \mathcal{F}(\mathbf{x}_n) + \text{noise}.$$

- ▶ Train a cGAN on \mathcal{S} .
- ▶ For a new test measurement \mathbf{y} , generate samples using g^* .
- ▶ Evaluate statistics using Monte Carlo.



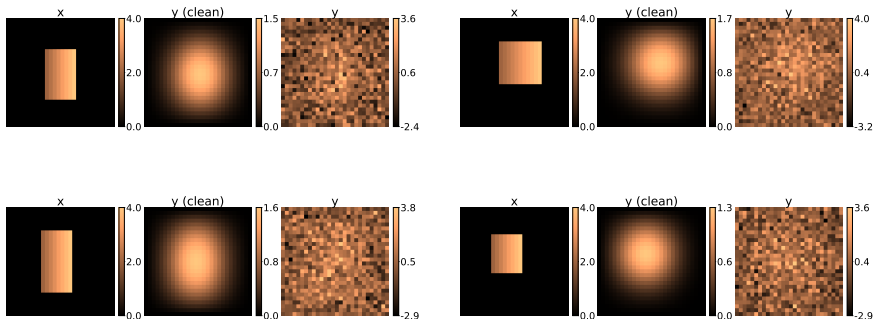
Consider the PDE

$$\begin{aligned}\frac{\partial u(\mathbf{s}, t)}{\partial t} - \nabla \cdot (\kappa(\mathbf{s}) \nabla u(\mathbf{s}, t)) &= 0, & \forall (\mathbf{s}, t) \in (0, 2\pi)^2 \times (0, 1] \\ u(\boldsymbol{\xi}, 0) &= u_0(\mathbf{s}), & \forall \mathbf{s} \in (0, 2\pi)^2 \\ u(\boldsymbol{\xi}, t) &= 0, & \forall \mathbf{s} \in \partial(0, 2\pi)^2 \times (0, 1]\end{aligned}$$

- ▶ \mathbf{x} : discrete initial temperature field.
- ▶ \mathbf{y} : noisy discrete final temperature field.
- ▶ \mathcal{F} : Finite difference solver for the PDE.
- ▶ We assume a constant κ .

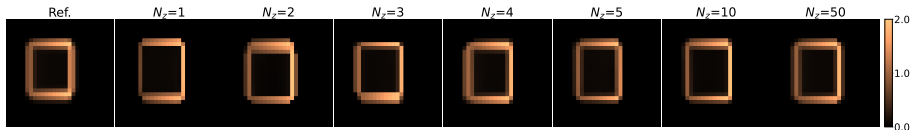
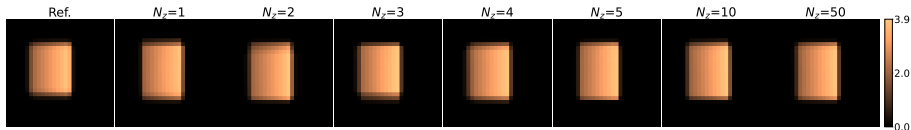
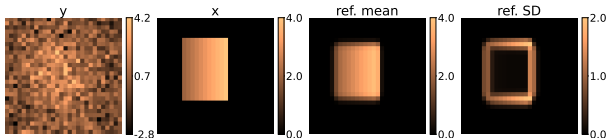
Assuming x to given by a rectangular inclusion and $N_x = N_y = 28 \times 28 = 784$

Training samples:



We don't have clean y in real problems!

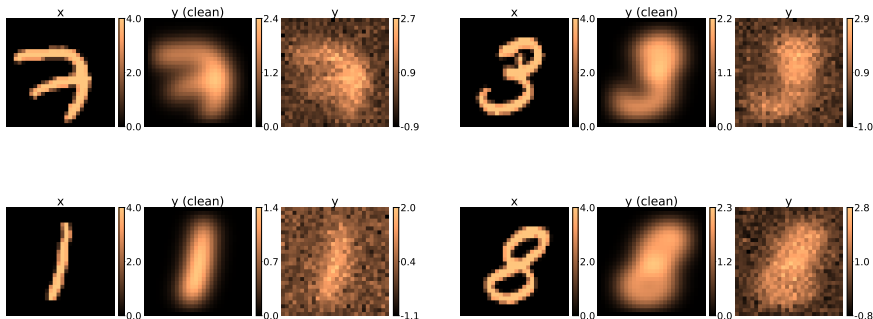
Testing trained cGAN (statistics with 800 z samples)



Assuming x to be given by (heat stamped) MNIST handwritten digits and

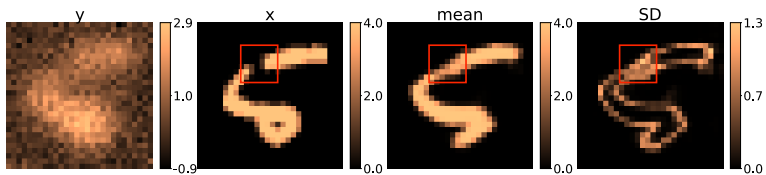
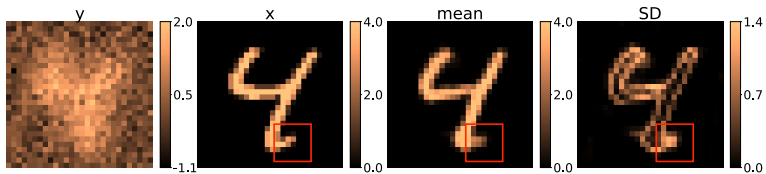
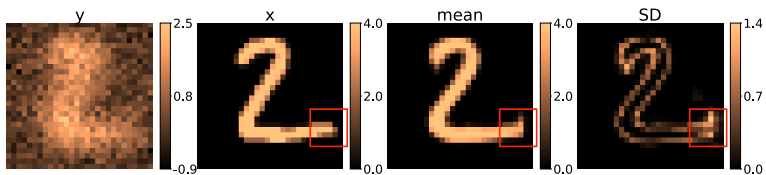
$$N_x = N_y = 28 \times 28 = 784$$

Training samples:



cGAN trained using latent dimension $N_z = 100$.

Testing trained cGAN (statistics with 800 z samples)

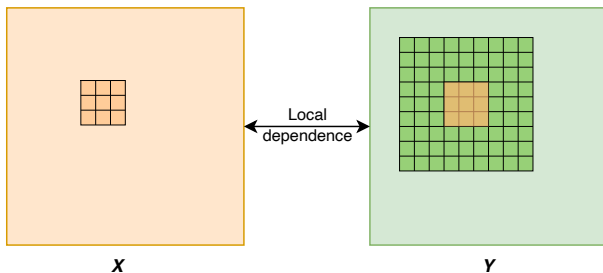


Generalization: cGAN trained on Set A gives good predictions on another distinct Set B, possibility sampled from a different distribution.

We can prove¹ the following: Assume

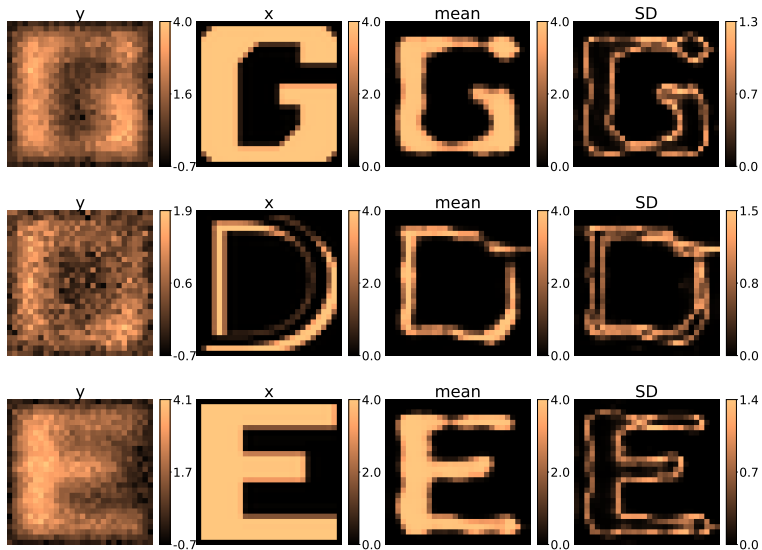
- ▶ The true (regularized) inverse map \mathcal{F}^{-1} is **spatially local**.
- ▶ Set A and Set B contain samples with **similar local spatial features**.
- ▶ A cGAN train on Set A, and is **also spatially local**.

Then the cGAN can generalize well to Set B.



1: *The efficacy and generalizability of conditional GANs for posterior inference in physics-based inverse problems* (D. Ray, D. Patel, H. Ramaswamy, A. A. Oberai); preprint 2022.

cGAN trained on MNIST, tested on notMNIST



- ▶ What do we gain?
 - ▶ Ability to represent and encode complex prior data.
 - ▶ Dimension reduction since $N_z \ll N_x$.
 - ▶ Sampling from cGAN is quick and easy.
- ▶ Need (x, y) pairs to train – supervised algorithm.
- ▶ Generalizability – training on smaller dataset.
- ▶ Currently testing algorithm on several other physics-based and medical applications.

Questions?

- ▶ U-Net architecture when x, y have tensored (image-like) structure.
- ▶ z injected through **conditional instance normalization**:
 - ▶ Can choose N_z independent of N_y .
 - ▶ Introduce stochasticity at multiple scales of U-Net.

